







ProMain Projet Aide Logiciel Kinematic

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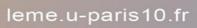
** Cogitobio - Osteobio







- 1. Télécharger et exécuter MCRInstaller.exe
- 2. Suivre les instructions
- 3. Exécuter le logiciel KinWin.exe
- 4. Changer la résolution d'écran: 1920x1080







Logiciel

4	Α	В	C	D	Е		F	G	H	Н	I	J	K		L	М	N	0	P	Q	R	S	Т	U	V	W	
1 De	vices																										
2	1000																										
3	AMTI OR6 Series Force Plate - CoP			late - CoP	AMTI OR6 Series Force Plate - Force			orce	AMTI OR6 Series Force Plate - Moment AM				AMTI OR6 Series Force Plate - Force (Re/			AMTI OR6 Series Force Plate - Moment			t Analog EMG	- Voltago							
4 Fra	ame	Sub Frame	Cx	Су	Cz	Fx		Fy	Fz		Mx	My	Mz	Fx	Fy		Fz	Mx	My	Mz	1	2	3	4	5	(6
5			mm	mm	mm	N		N	N		mm.N	mm.N	mm.N	N	N		N	mm.N	mm.N	mm.N	V	V	V	V	V	V	V
6	1	(171	.343 293.87	9	0	8.00636	-3.5	2498 -6	97.749	4271.04	-19995.5	-5159.11	1	-8.00636	3.52498	697.749	-4271.04	4 19	9995.5 5159.	L -0.00610352	0.0177002	0.00232697	-0.00476837	-0.00347137	0.00225067	7 0.0
7	1	1	171	.879 294.03	3	0	7.68402	-3.7	9635 -7	00.606	4180.26	-19702	-5294.5	5	-7.68402	3.79635	700.606	-4180.20	5	19702 5294	0.00427246	0.0228882	0.00167847	-0.00377655	-0.00267029	0.00152588	8 -0.0
8	1	2	171	.538 294.06	3	0	7.19096	-4.	2556 -7	00.786	4160.3	-19945.9	-5148.43	3	-7.19096	4.2556	700.786	-4160.3	3 19	9945.9 5148.	0.00061035	0.0210571	0.00400543	0.00461578	-0.0030899	0.00179293	1 -0.0
^	4		474	100 004 01	-	^	0 27720	2.2	F222 C	00 105	4177.01	20156.0	F1F0 30	-	0.27700	2 25222	COO 105	4177.0		0150 0							

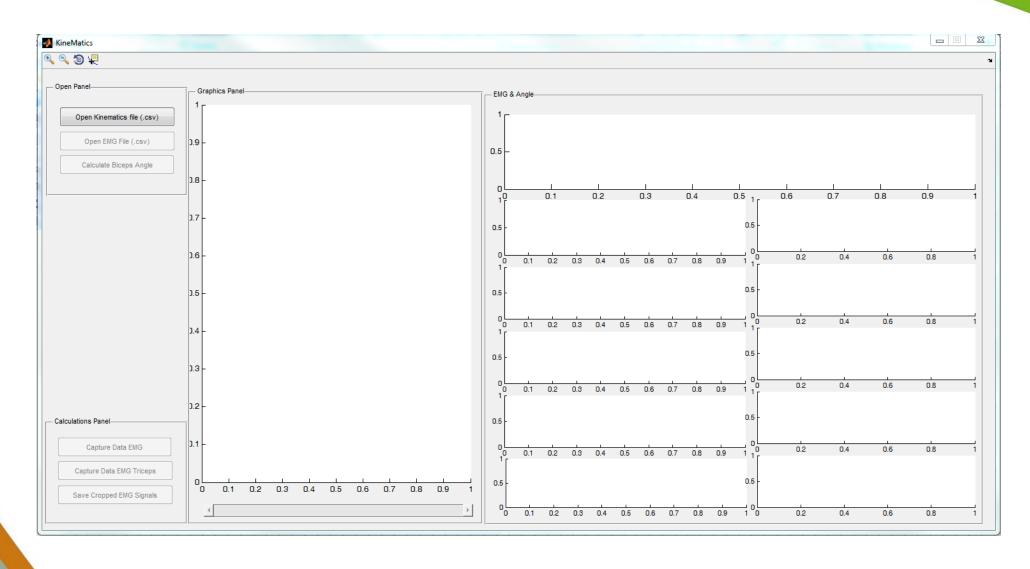
EMGSJ01CAL01.csv

89	/	1/1.352	295.05	U	8.40352	-2.20638	-695.763	3444.34	-19932.4	-5393.16	-8.40352	2.20638	695.763	-3444.34	19932.4	5393.16	-0.00259399	0.00183105	0.00415802	0.00358582
89	8	171.528	294.988	0	8.26713	-2.02799	-697.548	3495.89	-19860.9	-5315.91	-8.26713	2.02799	697.548	-3495.89	19860.9	5315.91	0.00198364	0.00030518	0.00919342	-0.00415802
89	9	171.321	295.094	0	8.26629	-1.979	-695.404	3411.61	-19943.4	-5431.86	-8.26629	1.979	695.404	-3411.61	19943.4	5431.86	-0.00289917	-0.00640869	0.0069046	0.00083923
Trajectories																				
100																				
		Cassandre O4:EIPS_G		Cassandre O4:EIPS_D			Cassandre O4:S1			Cassandre O4:L5		Cassandre O4:T12			Cassandre O4:Apex_lombaire			Cassandre O		
Frame	Sub Frame	X	Υ	Z	X	Y	Z	X	Υ	Z	X	Υ	Z	X	Y	Z	X	Y	Z	X
y .		mm	mm	mm	mm	mm	mm	mm	mm	mm	mm	mm	mm	mm	mm	mm	mm	mm	mm	mm
1		224.032	428.201	663.516	329.864	441.744	658.888	276.765	438.961	646.571	281.072	433.359	688.897	287.469	429.018	852.015	282.784	426.316	760.382	293.638
2		224.014	428.192	663.514	329.86	441.739	658.92	276.742	438.985	646.582	281.072	433.359	688.897	287.444	428.984	852.003	282.783	426.318	760.368	293.636
3		223.991	428.216	663.524	329.859	441.741	658.906	276,742	438.985	646.582	281.072	433.359	688.897	287,444	428.984	852.003	282.776	426.293	760.358	293.617

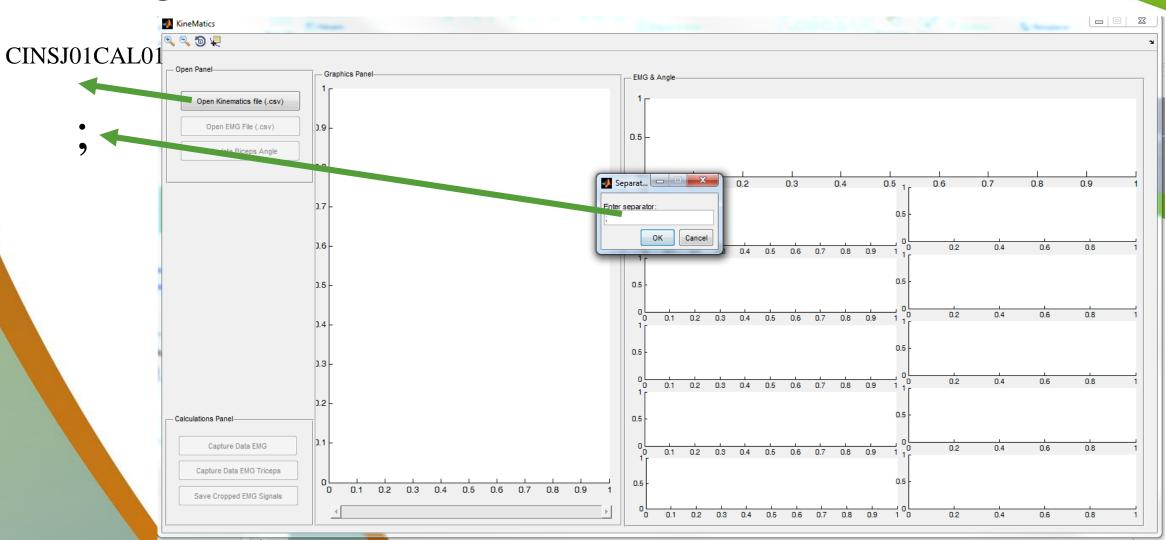
CINSJ01CAL01.csv

SUJET	NOM
1	Cassandra

Logiciel



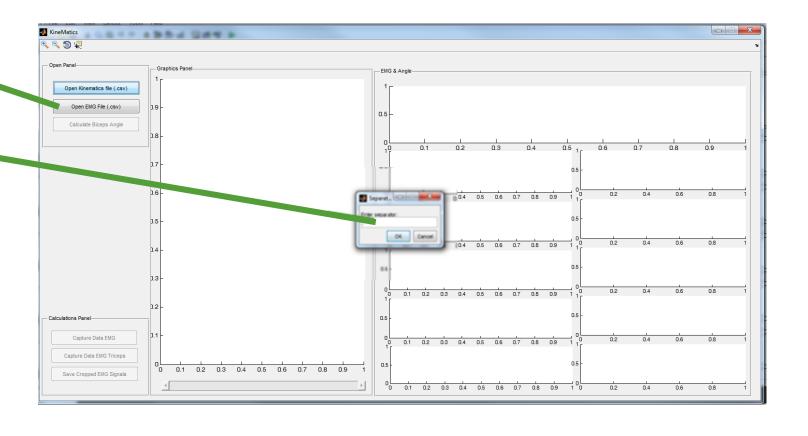




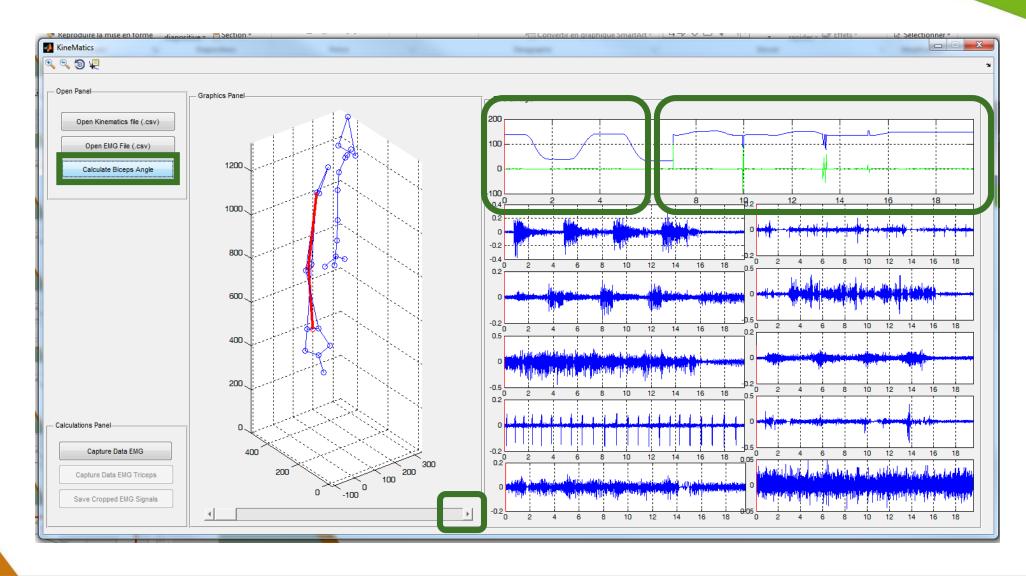
Logiciel

EMGSJ01CAL01.csv

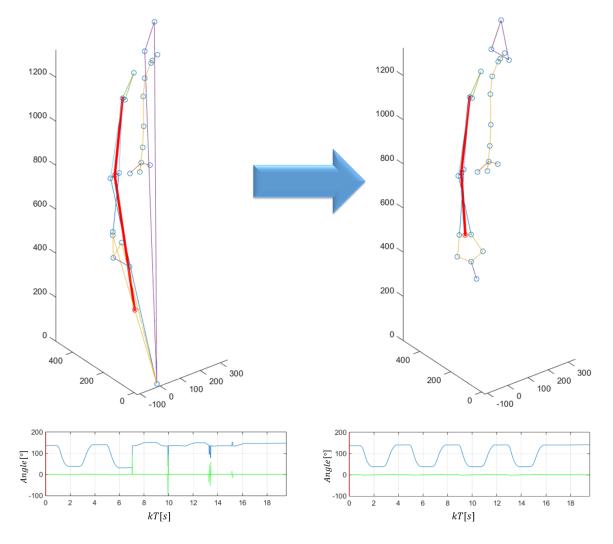
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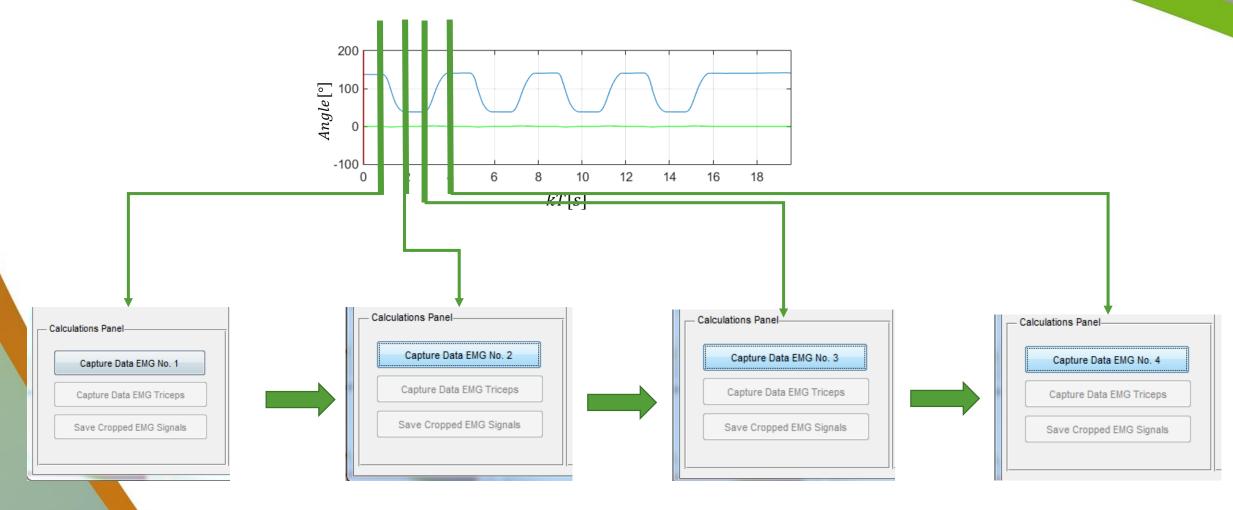
Logiciel – Vérification Cinématique



Logiciel – Vérification Cinématique



Logiciel – couper des signaux



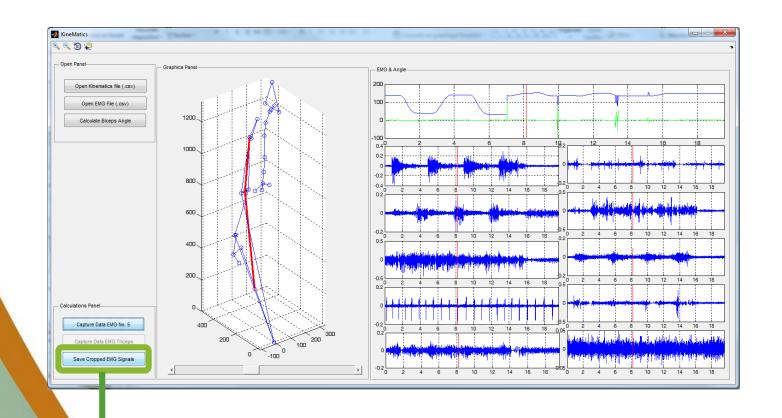
Début de flexion

Fin de flexion

Début de extension

Fin de extension

Logiciel – sauver



CroppedEMGData.mat CroppedEMGDataSJ01TR01CAL01.mat